$\hat{p}$ r $\sigma \hat{j}e$ c $au^{_{152}}$ 

# Phase 11

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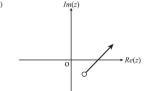
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## Question 1

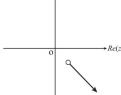
### **QUESTION 10**

The subset of the complex plane that represents  $\arg[z+i-1]+\frac{\pi}{4}=0$  for  $z\in C$  is

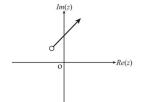
(A)



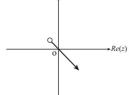
(B)



(C)



(D)



Im(z)

## Question 2

**QUESTION 8**Use the substitution  $u = \tan(x)$  to determine  $\int \tan(x) \sec^2(x) dx$ .

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(A)  $\frac{1}{2}\tan(x)+c$ 

(B) 
$$\frac{1}{2} \tan^2(x) + c$$

- (C)  $\tan(x) + c$
- (D)  $\tan^2(x)+c$

### Question 3

**QUESTION 4** 

When using proof by mathematical induction to prove De Moivre's theorem expressed as  $(r \operatorname{cis}(\theta))^n = r^n \operatorname{cis}(n\theta) \, \forall n \in \mathbb{Z}^+$ , which statement would be correct in the proof of the inductive step?

(A) 
$$(r \operatorname{cis}(\theta))^k = r^k \operatorname{cis}(k\theta)$$

(B) 
$$(r \operatorname{cis}(\theta))^k = r^{k+1} \operatorname{cis}(k+\theta)$$

(C) 
$$(r\operatorname{cis}(\theta))^{k+1} = r^{k+1}\operatorname{cis}(k\theta+1)$$

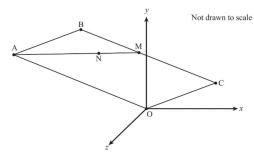
(D) 
$$\left(r\operatorname{cis}(\theta)\right)^{k+1} = r^{k+1}\operatorname{cis}\left((k+1)\theta\right)$$

## Question 4

QUESTION 15 (6 marks)

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The points O(0,0,0), A(-6,2,-2) and C(3,1,2) are represented in three-dimensional space in the diagram.



OABC forms a parallelogram in three-dimensional space.

a) Determine the coordinates of B.

[1 mark]

M is the midpoint of BC.

b) Determine the vector that represents  $\overrightarrow{OM}$ .

[1 mark]

N divides AM in the ratio 2:1.

c) Determine the vector that represents  $\overrightarrow{ON}$ .

[2 marks]

d) Use a vector method to show that O, B and N lie on a straight line.

[2 marks]

### Question 5

**QUESTION 19 (7 marks)** 

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The velocity vectors of two objects A and B (in m s<sup>-1</sup>) at time t (in s) are given respectively by

$$v_{A} = 6\sin(3t)\hat{i} + 6\cos(3t)\hat{j}$$
$$v_{B} = \cos(t)\hat{i} - \sin(t)\hat{j}$$

Objects A and B are initially at (-2, 0, 2) and (0, 1, -1) respectively. Determine the position of Object A when it is 4 metres away from Object B for the first time.